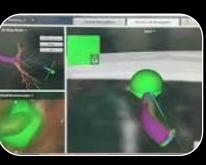
Real-time Image-guided Electromagnetic Navigational Bronchoscopy Dual-marker Technique to Localize Deep Pulmonary Nodules in A Hybrid Operating Room

<u>Chih-Tsung Wen</u>, Hsin-Yueh Fang, Chien-Hung Chiu, Ching-Feng Wu, Wei-Hsun Chen, Ching-Yang Wu, Ming-Ju Hsieh, Yi-Cheng Wu, Yin-Kai Chao, Yun-Hen Liu, Hui-Ping, Liu <u>溫志聰</u>, 范馨月, 邱健宏, 吳青峰, 陳維勳, 吳青陽, 謝明儒, 吳怡成, 趙盈凱, 劉永恆, 劉會平 林口長庚醫院 胸腔外科

Localization of lung nodules



CT-guided





Zeego

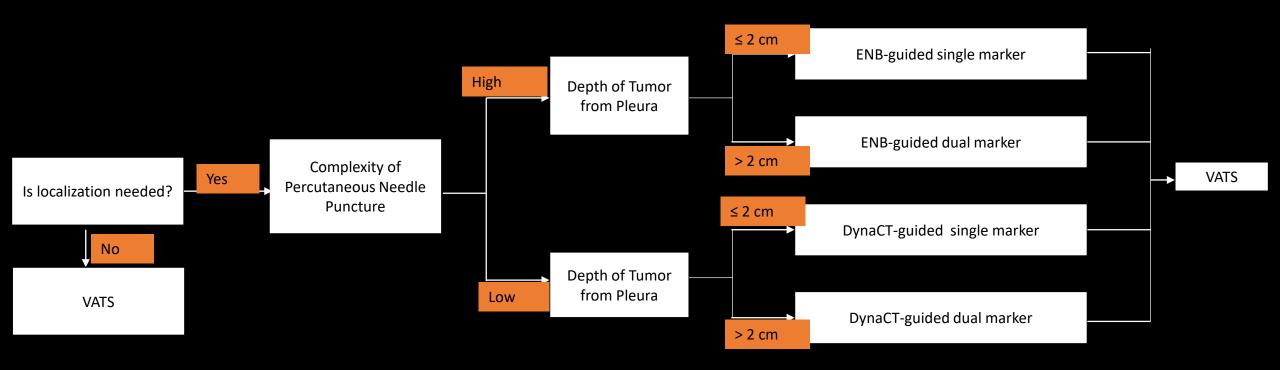


ENB Guide dual localization

| percutaneous | | | localization | |
|--------------|--------------|--------------|--------------|--------------|
| Location | CT room | OR | Hybrid OR | Hybrid OR |
| Puncture | Percutaneous | Bronchoscopy | Percutaneous | Bronchoscopy |
| Image guide | Real-time | Virtual | Real-time | Real-time |

ENB-guided

Personalized Approach for Small Lung Tumor Localization & Surgery





Localization of lung nodules

CT-guided percutaneous puncture

| Location | CT room |
|-------------|------------------|
| Puncture | Percutaneous |
| Image guide | Real-time |

Pneumothorax

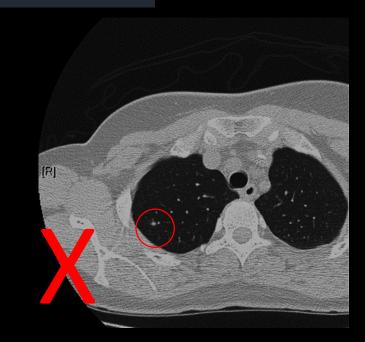


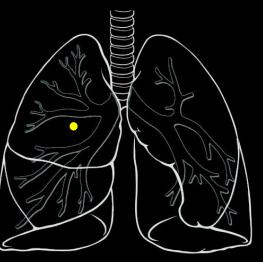
Small and deep pulmonary nodules are sometimes difficult to localize percutaneously

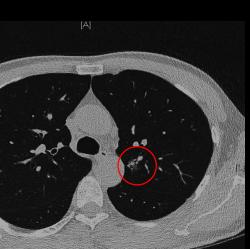
Difficulties in percutaneous localization

Risk of puncture central nodules near pericardium& major vessels

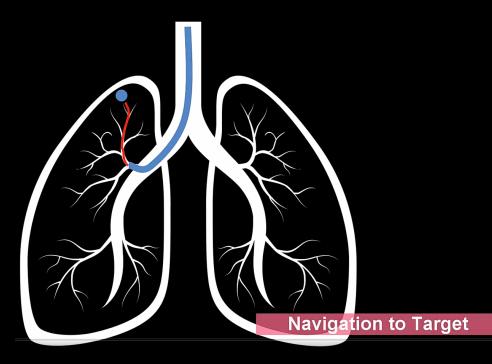
> Scapula impediment under the puncture site



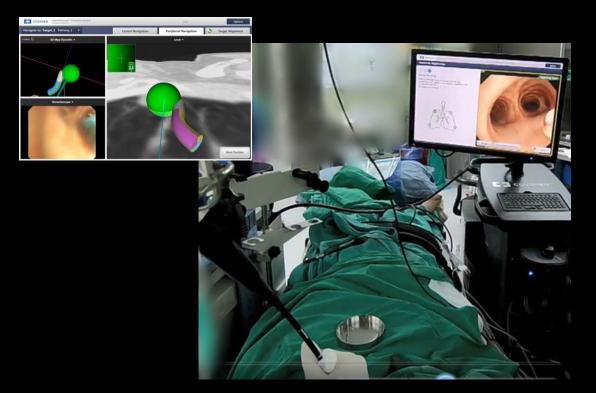




ENB-guided localization



| Location | OR | |
|-----------------|--------------|--|
| Puncture | Bronchoscopy | |
| Image guide 🛛 🤇 | Virtual | |

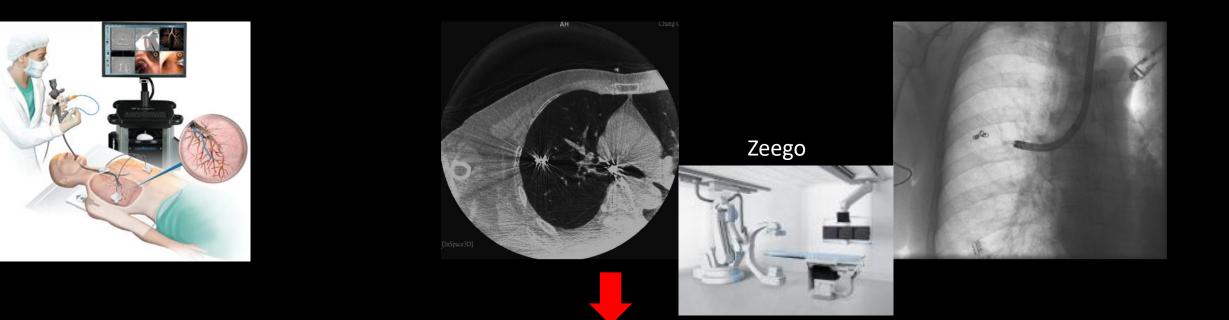


Accuracy affected by Respiratory movement

Small and deep pulmonary nodules are sometimes difficult to localize percutaneously

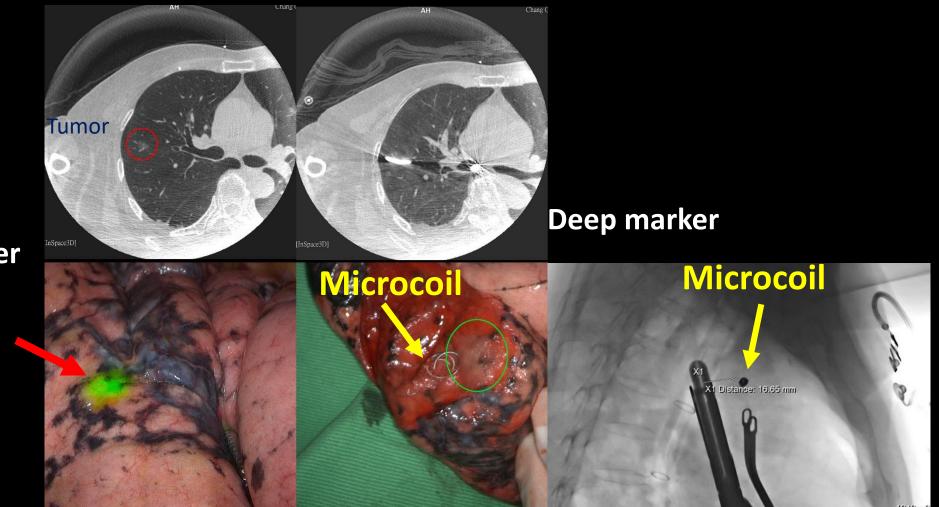
> ENB-guided localization Real-time?

ENB + Dyna CT + Flouroscopy



Real-time Image-guided Electromagnetic Navigational Bronchoscopy

Real-time ENB-guided dual marker localization



Superficial marker

ICG

Study aim

 The goal of this study was to evaluate the safety and effectiveness of this real-time image-guided electromagnetic navigational bronchoscopy dual-marker technique.

Material and methods

Patient recruit

Single center retrospective study

• Chang Gung Memorial Hospital (Linko, Taiwan)

Duration

• August 2018 to January 2019

Case number

• N=15

Operation method

• Patient underwent real- time ENB dual marker localization for resections of single lung nodule

Equipment

• Hybrid OR and ENB system

Inclusion and exclusion

Inclusion criteria

- deep locationed nodules(>1cm from the visceral pleural surface)
- solid nodules with small size (<1cm)

Exclusion criteria 1) nodules <1cm deep from pleural surface 2) pulmonary lesion that are not amenable to wedge resection (ie. pure GGO>2cm and lung nodule with solid part>1cm)

Dyna-CT guided Electromagnetic Navigation Bronchoscopic Dual marker Placement for Deep Pulmonary Tumor

Yin-Kai Chao MD/ Ph.D Chief ,Division of Thoracic Surgery Chang Gung Memorial Hospital, Linkou, Taiwan chaoyk@gmail.com



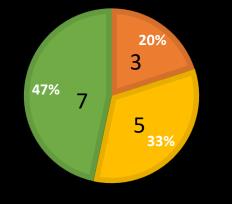
Result

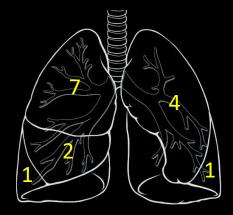
Demographic result

| N=15 | Median (IQR) |
|-----------------------------|------------------|
| Age, years (median; IQR) | 58 (45-64) |
| Sex, number | |
| Male | 9 |
| Female | 6 |
| Lesion size, cm | 1.0 (0.6-1.3) |
| Lesion depth, cm | 1.8 (1.6-3.4) |
| Depth-to-size ratio | 2.83 (1.78-3.10) |

LESION DEPTH

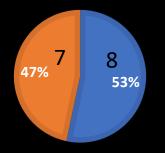
central middle peripheral





MORPHOLOGY

Solid Subsolid/GGO



Localization Result

| | Median (IQR) |
|--|-------------------------|
| Localization procedural time, min | 35 (26-44) |
| Time from 1st DynaCT to needle puncture, min | 8 (5-15) |
| Time from localization to surgery, min | 40 (32-49) |
| Number of DynaCT scans | |
| 2 | 9 (60%) |
| 3 | 4 (27%) |
| 4 | 2 (13%) |
| Radiation effective dose, mSv | 15.97 (8.98-21.6) |
| Distance from coil to nodule center, cm | 0.8(0.4-1.4) (max: 1.5) |
| Pneumothorax | nil |

Surgical Result

| | Median (IQR) | |
|------------------------|----------------------------------|--|
| Operating time, min | 74 (57-125) | |
| Resection method | | |
| Wedge resection | 9 (60%) | |
| Wedge->Lobectomy | 2 (13%) | |
| Segmentectomy | 4 (27%) | |
| LOS, days | 3 (2-4) | |
| Pathological diagnosis | | |
| Benign | 6 (40%) | |
| Primary malignancy | 7 (47%) | |
| Metastatic tumor | 2 (13%) | |
| Margin, cm | 1.5 (1.0-1.7) (min:0.5; max:7.6) | |

Discussion

Features of real-time ENB dual localization

ENB guide localization does not require skin puncture / wires

• Pneumothorax \checkmark

Features of ENB dual localization

ENB guide localization does not require skin puncture / wires

• Pneumothorax \checkmark

Real-time image guidance(Zeego system) during ENB

• Minimizing discrepancies induced by respiratory movements

Features of ENB dual localization

ENB guide localization does not require skin puncture / wires

• Pneumothorax \checkmark

Real-time image guidance(DynaCT +fluoroscopy) during ENB

• Minimizing discrepancies induced by respiratory movements

Easier to approach deep lesions (difficult /risky for percutaneous puncture)

• Lesions located in the lung apex, in proximity of the diaphragm or major mediastinal organs, or behind the scapula

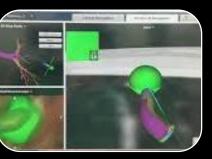
Limitation

- Small case number (N=15)
- Relative longer localization time
- Radiation exposure (Dyna-CT and fluoroscopy)

localization of lung nodules



CT-guided percutaneous



ENB-guided



Zeego



Real-time ENB Guide localization

| Location | CT room | OR | Hybrid OR | Hybrid OR |
|-------------------------|--------------|--------------|--------------|--------------|
| Puncture | Percutaneous | Bronchoscopy | Percutaneous | Bronchoscopy |
| Pnuemothorax | Possible | Less | Possible | Less |
| Image guide | Real time | Virtual | Real time | Real time |
| Radiation exposure | Yes | Nil | Yes | Yes |
| Time delay(puncture-OP) | Longer | Shorter | Shorter | Shorter |



• This study indicates that real-time ENB Dual Marker localization is a safe and accurate intraoperative modality for targeted sublobar resection of pulmonary nodules that are deemed difficult to localize.

Thank you for listening!